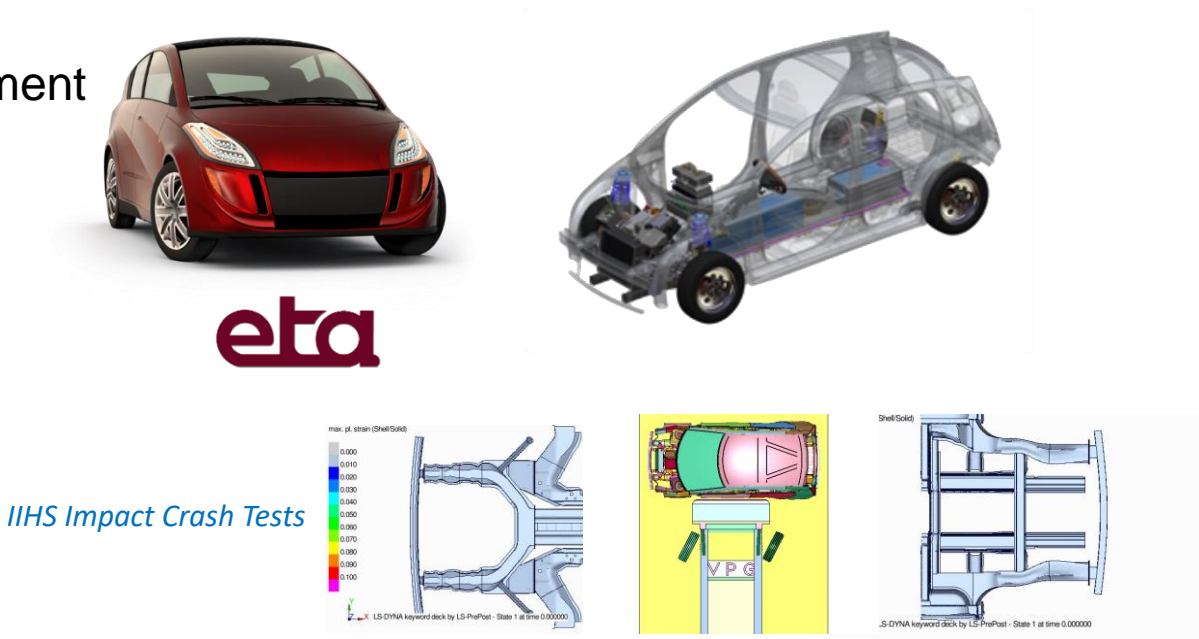


# World Auto Steel

## Future Steel Vehicle

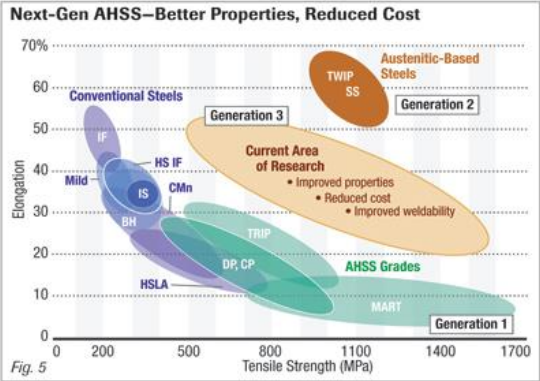
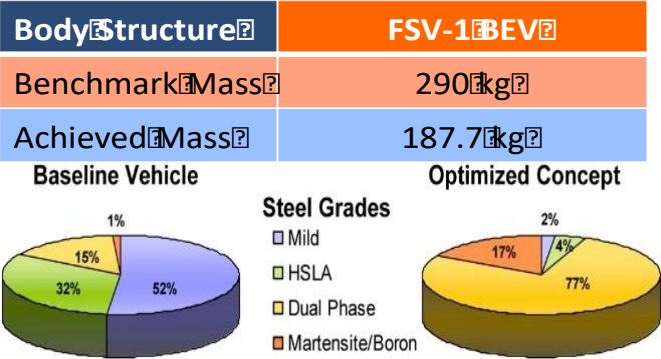
### Challenge:

- Use a new performance-driven, holistic product development process (ACP) based on HEEDS to minimize mass of new Battery Electric Vehicle
- Loading conditions
  - Crash (LS-Dyna), NVH (Nastran), Handling (ADAMS)
- Design variables
  - Geometry, Gauge, Grade (AHSS)



### Results:

- ✧ 35% Mass Savings
- ✧ 5-Star Crash Safety Rating
- ✧ 70% Emissions Reduction
- ✧ No Cost Penalty



# Customer Success: Electric Motor Design Study

## Challenge

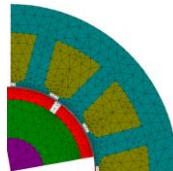
- Minimize cogging torque
- Design variables
  - $100^\circ < \text{Magnet Pole Arc} < 180^\circ$
  - $1 \text{ mm} < \text{Slot Opening (SO)} < 4 \text{ mm}$
  - $0.3 \text{ mm} < \text{Air Gap (Gap)} < 2 \text{ mm}$

## Results

- 99% lower cogging torque

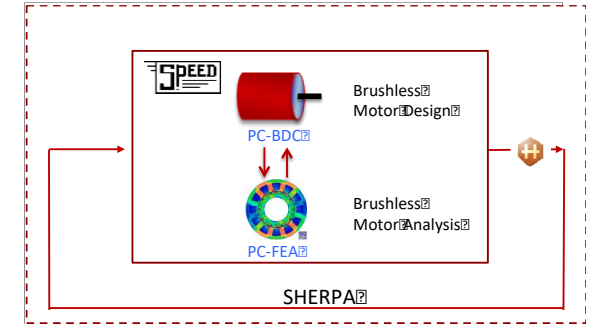
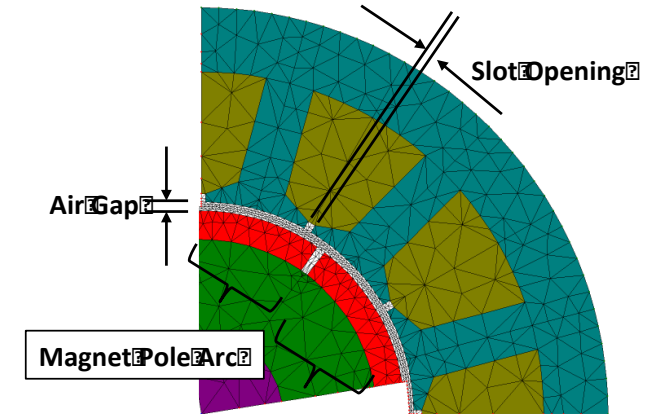
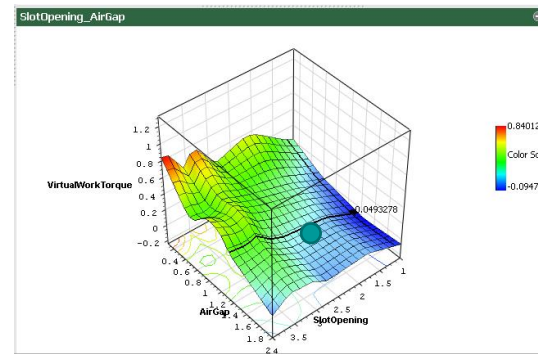
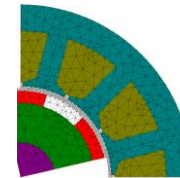
### Baseline Design:

- Cogging Torque= 0.7185 Nm
- Magnet Pole Arc =  $170^\circ$
- Slot Opening (SO) = 3.0 mm
- Air Gap (Gap) = 0.5 mm



### Improved Design:

- Cogging Torque= 0.004 Nm
- Magnet Pole Arc =  $123^\circ$
- Slot Opening (SO) = 1.15 mm
- Air Gap (Gap) = 1.35 mm



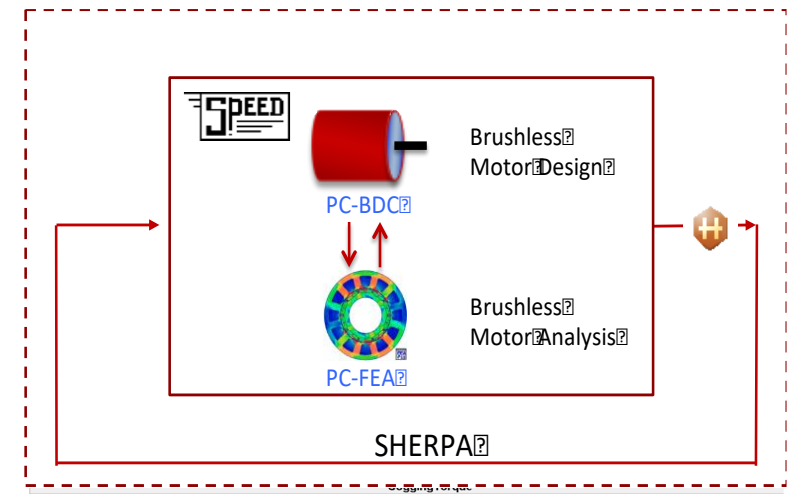
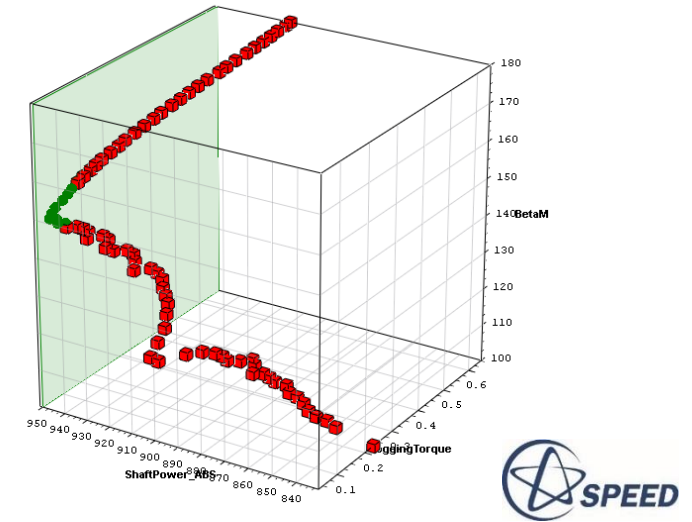
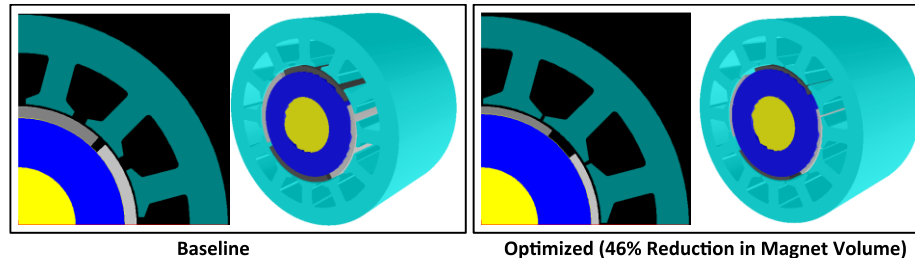
# Customer Success: Electric Motor Design Study

## Challenge:

- Minimize cogging torque and magnet volume
- Constraints (8):
  - $950 \text{ W} < \text{Shaft Power} < 1050 \text{ W}$
  - $190 \text{ V} < \text{Induced Voltage} < 200 \text{ V}$
  - $\text{Copper Losses} < 100 \text{ W}$
  - $\text{Iron Losses} < 20 \text{ W}$
  - $\text{Total Losses} < 120 \text{ W}$
  - $1.4 \text{ T} < \text{Stator Flux Density} < 1.6 \text{ T}$
  - $1.4 \text{ T} < \text{Stator Yoke Flux} < 1.6 \text{ T}$
  - $\text{Rotor Yoke Flux Density} < 1.6 \text{ T}$
- Design variables (10):
  - $100^\circ \leq \text{Magnet Pole Arc} \leq 180^\circ$
  - $1 \text{ mm} \leq \text{Slot Opening} \leq 4 \text{ mm}$
  - $0.3 \text{ mm} \leq \text{Air Gap} \leq 2 \text{ mm}$
  - $10 \text{ mm} \leq \text{Slot Depth} \leq 17 \text{ mm}$
  - $50 \leq \text{Number of Coils} \leq 150$
  - $60 \text{ mm} \leq \text{Stack Length} \leq 80 \text{ mm}$
  - $4 \text{ A} \leq \text{Current Set Point} \leq 7 \text{ A}$
  - $5 \text{ mm} \leq \text{Tooth Width} \leq 10 \text{ mm}$
  - $1 \text{ mm} \leq \text{Magnet Thickness} \leq 5 \text{ mm}$
  - $26 \text{ mm} \leq \text{Outer Rotor Radius} \leq 36 \text{ mm}$

## Results:

- 94% reduction in cogging torque
- 46% reduction in magnet volume



# Michigan Economic Development Cooperation

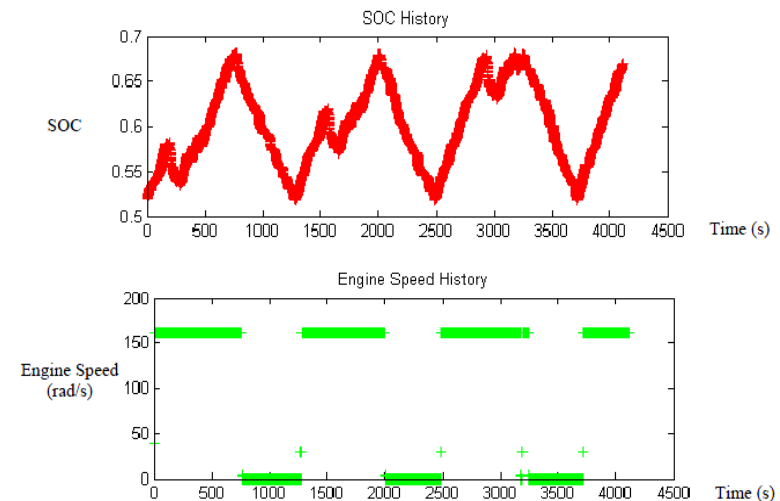
## Hybrid Bus Design

### Challenge:

- Maximize fuel economy for a series hybrid electric bus
- Constraints
  - Missed trace less than 5 mph
  - Maintain a battery charge greater than 51.75 %
  - Accelerate from 0-60 mph under 42 seconds
  - Accelerate from 0-30 mph under 10 seconds
- Design variables
  - Engine size, battery pack, electric motor, generator

### Results:

- Increased fuel economy by 9%
- Decreased missed trace from 15.7 mph to < 2.5 mph
- Decreased 0–60 acceleration time from 53 s to 25 s
- Decreased 0–30 acceleration time from 21 s to 7 s





# Streamlining the Design Exploration Process

## Application Example Excavator Performance Improvement with Electric Swirl Motor

### Objective:

- Minimize operation cycle time
- Minimize fuel consumption

### Design variables (5):

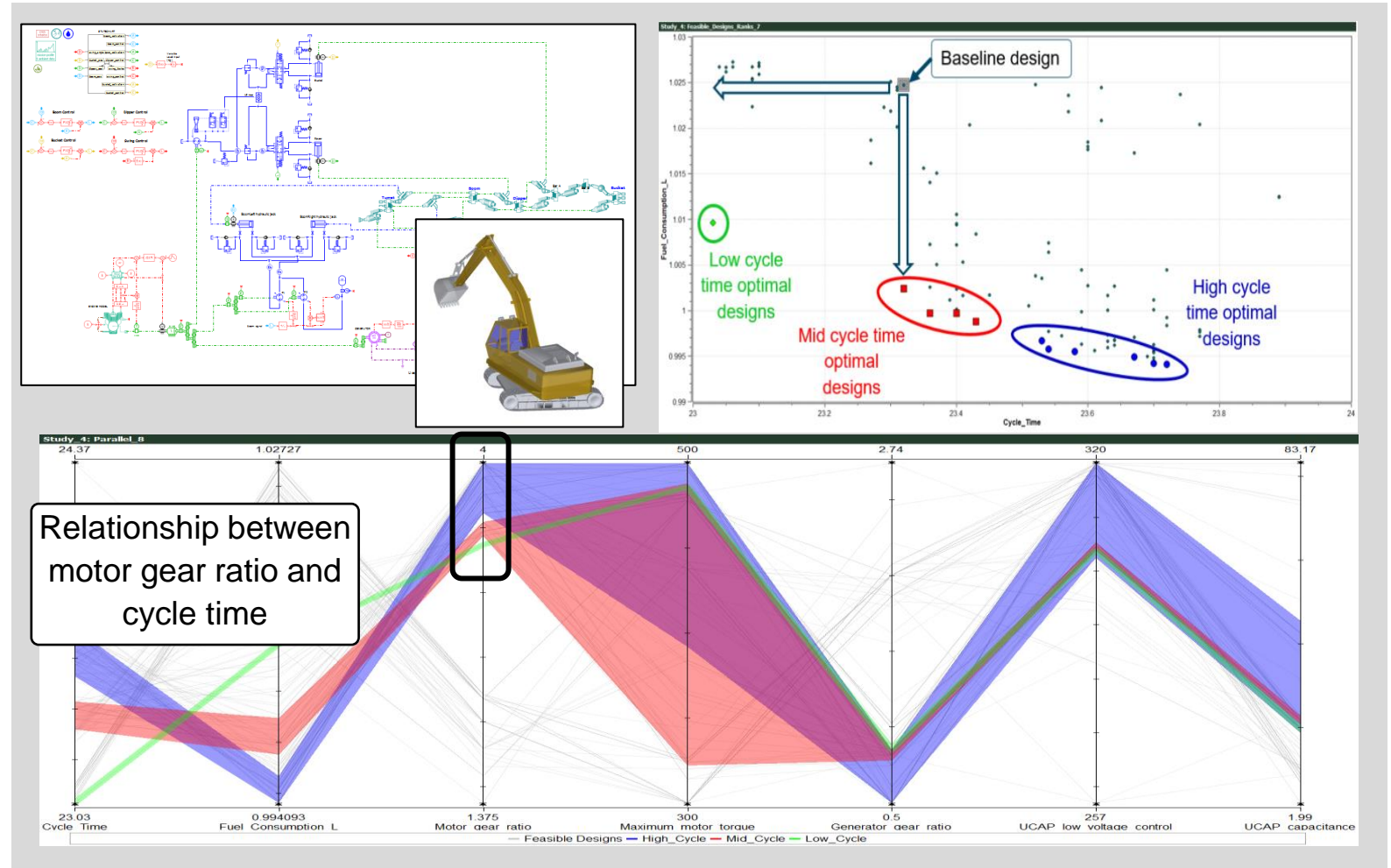
- Electric motor torque
- Gearbox gear ratios
- Ultra capacitor size, and control scheme

### Results:

500 design evaluations were performed

Designs were discovered which improved cycle time and fuel consumption compared to the original design

Discovered tradeoff relationship between fuel consumption and cycle time



# Customer Success: Performance, Range & Comfort

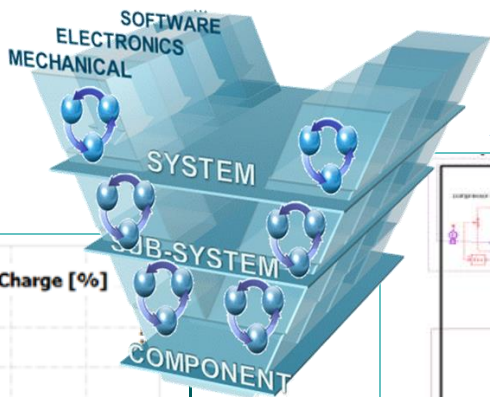
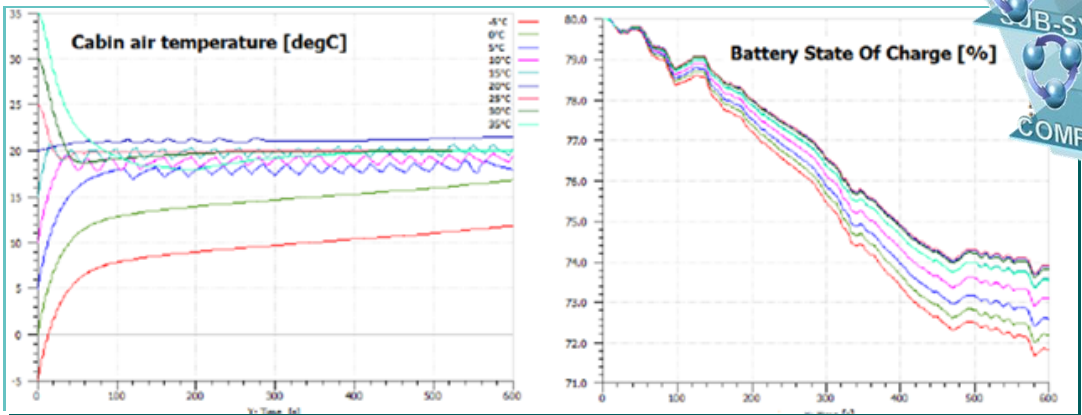
## Challenge:

- Balance performance, range, and passenger comfort of an electric vehicle
- AMESim and Matlab/Simulink used to simulate 1D system behavior
- HEEDS adjust bypass orifice to improve system performance

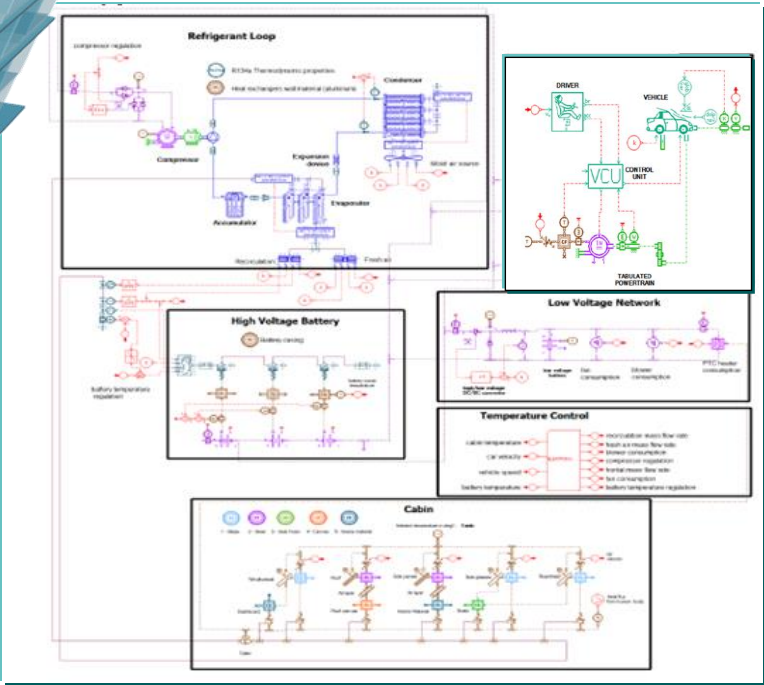


## Results:

- Best balance achieved



AMESim 1-D Subsystem Models



# Streamlining the Design Exploration Process

## Application Example: Electric Vehicle Sizing

### Objective:

- Minimize acceleration time (0 -100 km/h)
- Maximize range

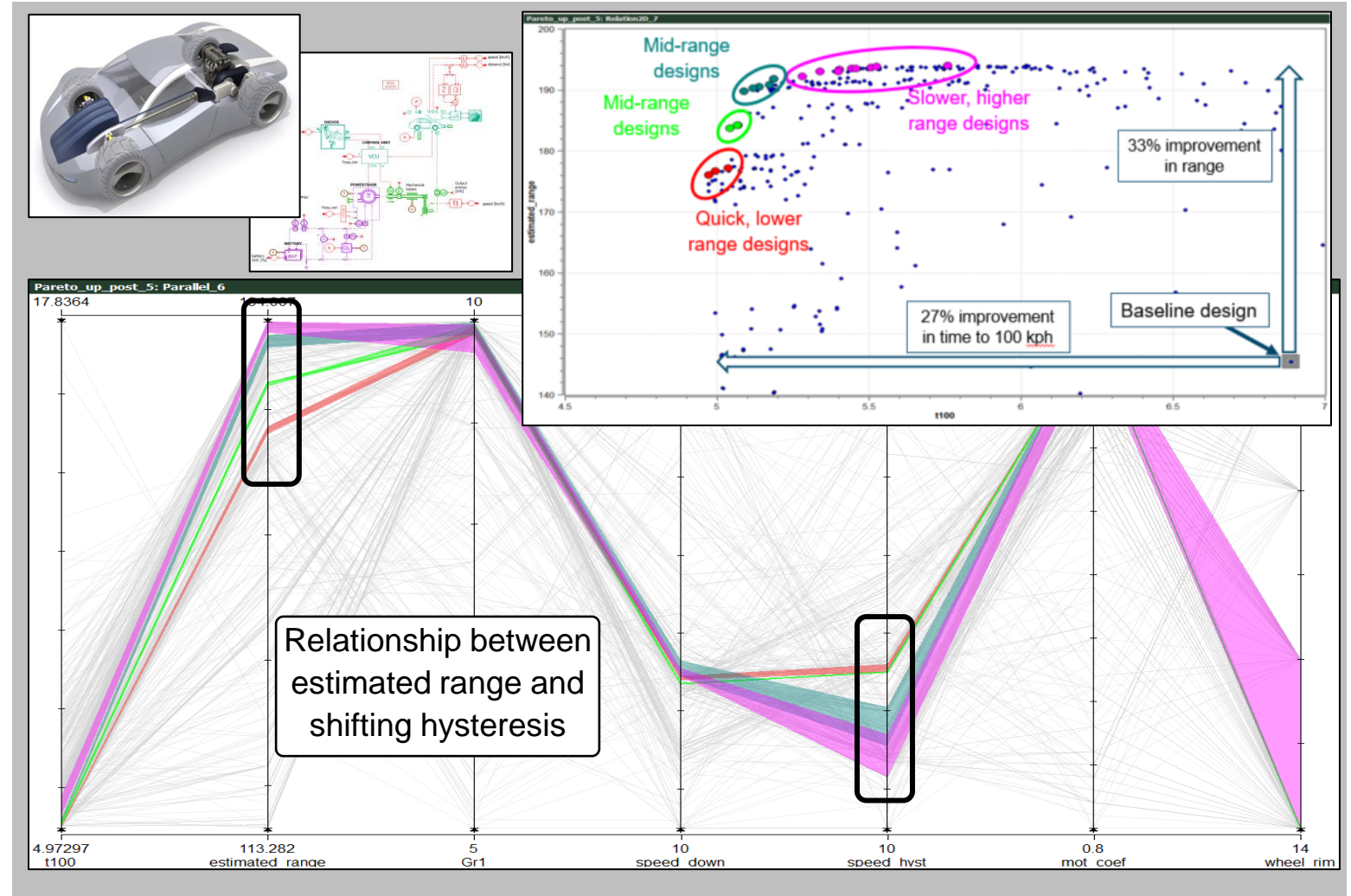
### Design variables (5):

- Torque Curve Coefficient
- Gear Ratio
- Downshift Speed
- Shifting Hysteresis
- Rim Diameter

### Results:

500 design concepts were evaluated in five hours of simulation clock-time (5 cores used on Windows laptop)

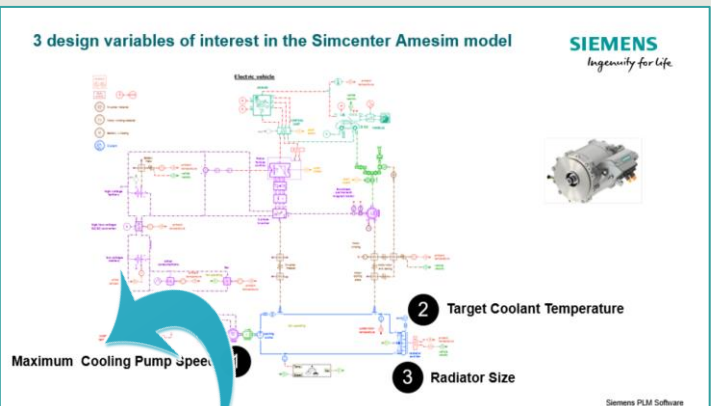
Discovered tradeoff relationship between goals, with improvement over starting design ranging from 27% gain in acceleration to 33% longer range



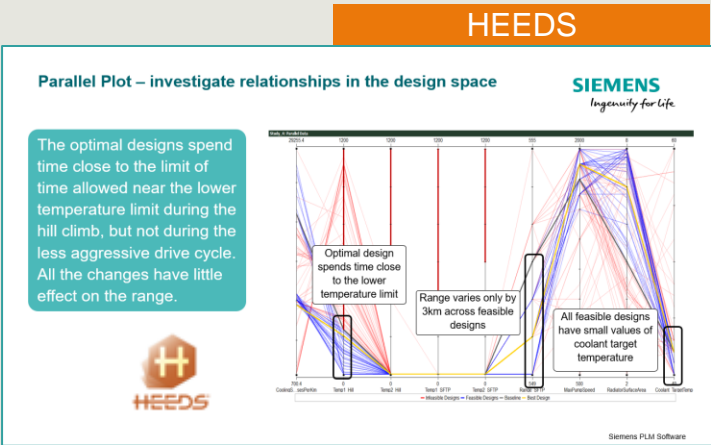
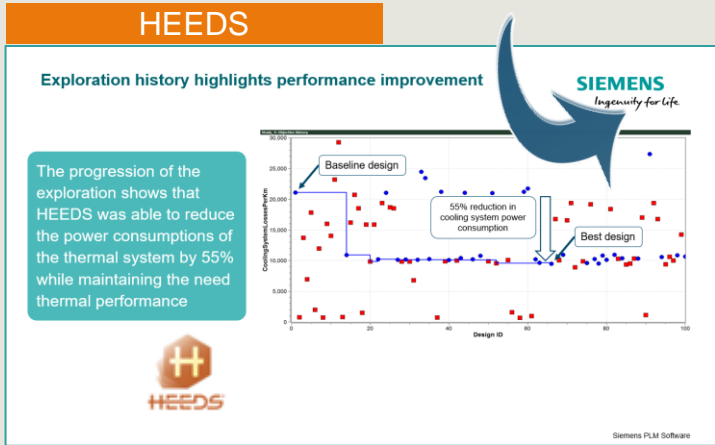


# Simcenter™

## Sizing an electric vehicle for optimal thermal performance



Simcenter Amesim



**Challenge**

The cooling system design of electric vehicles affects the thermal system performance and range, making it critical to find the best design.

**Solution**

Simcenter Amesim for electric vehicle thermal sizing coupled with HEEDS to scan the design space, in order to reduce the cooling system power requirements.

- Benefit**
- Find optimal cooling systems without affecting thermal performance and range
  - Shorten product development time
  - Validate the cooling control system



# Valeo EEM

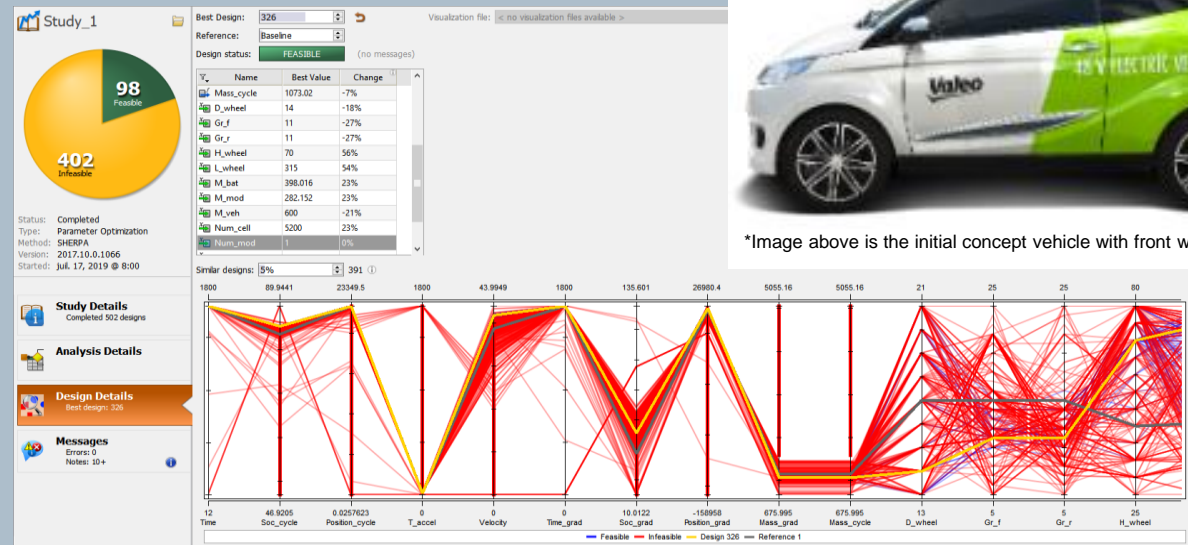
## Design Optimization of EV Architecture



### Results:

- In 500 iterations, HEEDS improved the overall performance of a 4 wheel drive vehicle
- Reduced acceleration time by 14%
- Increased max. speed by 5%
- Increased vehicle range (WLTC Class 3) by 11%
- Reduced mass by 8%

### Final Design



\*Image above is the initial concept vehicle with front wheel drive

\* The HEEDS simulation study above is for a 4WD design

**HEEDS improved all 8 objectives in a single study, while satisfying all the constraints!**